On page 4, line 21 to page 5, line 2, please replace the paragraph with the following

amended paragraph:

As shown particularly in Fig. 4, the control mechanism 7 is placed between the

working base 9 (in reality, in horizontal position VA) and the bottom part 3 of the cabin

element 4 (in reality, tilted according to the frame position KA) so that the first 7a and second

7b means of the control mechanism 7 for tilting the working base are placed, in the height

direction, underneath the third 7c means of the control mechanism 7. Furthermore, the

movements of the first 7a and second 7b means of the control mechanism 7 for tilting the

working base 9 are arranged to be effected around a substantially joint movement center

LKP, wherein this movement center LKP is preferably on the Z axis and placed above the

seat part 5a of the seat 5 intended for the operator K of the working machine 2, preferably to

be placed substantially at the level of the operator's K hip, as shown in Fig. 5. The detailed

structure of the control mechanism 7 itself will not be described in this context, because e.g.

the applicant's previous FI patent application 991449 discloses a position adjustment

mechanism which can, when modified, also be applied in the applications of the present

invention.

On page 5, line 14 to page 6, line 11, please replace the paragraph with the following

amended paragraph:

A cover arrangement 10a, 10b is placed in the point of linkage between the bottom

part 3 and the working base 9 to connect the working base 9, separate from the control

mechanism 7, to the cabin element 4 during their respective movements. The cover

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arrangement 10a, 10b preferably consists of two parts in such a way that its first part, the annular collar part 10a, i.e. the annular collar part which is connected to the outer edge of the working base 9, at least its outer surface having a spherical shape, extends downwards, and the second part 10b consists of that part of the inner surface 3a of the bottom part 3 which is exposed during the movements of the working base 9, as shown in Fig. 4. To provide the system of movements presented above, it is advantageous that the shape of the bottom part 3 of the cabin element 4, at least of the inner surface 3a, at least on that range of height dimension in which the working base 9 moves during the respective movements of the working base 9 and the frame of the working machine 2, is a spherical surface, preferably so that the whole bottom part 3 of the cabin element 4, at least on the side of the inner surface, is substantially spherical. In the embodiment presented in the drawings, the bottom part 3 is, substantially as a whole, a sheet-like form piece with a spherical shape, whose upper edge 3b is connected to a substantially horizontal collar part 11 formed at the lower edge 4a of the cabin element 4. Thus, in the presented embodiment, the horizontal cross-section of the bottom part 3 of the cabin element 4 reduces downwards, which makes it possible to save space, particularly in the height direction of the working machine. Furthermore, the center KK of the spherical form of the inner surface 3a of the bottom part 3 (Fig. 4) is placed above the seat part 5a of the seat 5, by the hip of the operator K. Preferably, the center KK joins the movement center LKP (see also Fig. 5). The diameter of the circular working base 9 is selected so that it is substantially placed in the upper part of the spherical shape of the bottom part 3, touching the spherical shape at the whole length of its circumference, wherein the annular collar part 10a, whose outer surface has an at least spherical shape and which forms

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the first part of the cover arrangement 10a, 10b, is placed on the inner surface 8a of the bottom part 3.

In the paragraph on page 6, line 12, please amend the paragraph as follows:

The present invention is not limited solely to the above-presented and exemplified preferred embodiments but it can be modified within the scope of the appended claims.